



Key features

Design

General

The SMAT-8M is a position transmitter for the contactless sensing of the piston position of drives that can be detected magnetically. It supplies a displacement-proportional analogue output signal in the position measuring range. It is connected directly to the analogue PLC inputs without any accessories. With its extremely compact design,

the SMAT-8M is the ideal solution for grippers, short-stroke cylinders and all applications in which installation space is restricted.

Note

It can be used with Festo cylinders with T-slot (profile slot 8) as well as round cylinders and tie-rod cylinders with mounting kits. A selection aid with suitable drives can be found on the following pages.

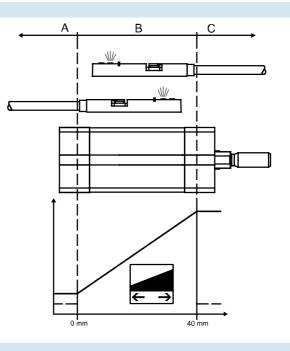
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Position measuring range

The SMAT-8M supplies a displacement-proportional analogue output signal of 0 ... 10 V in the position measuring range of up to 40 mm (depending on the drive used). In other words, the output voltage increases when the piston moves in the direction of the piston rod. When the piston retracts, the output voltage drops.

The installation direction of the SMAT-8M is irrelevant in this case. To achieve the best possible function on the drive in question, the position measuring range must be initialised on the drive during installation.

As a visual aid, the green LED lights up within the position measuring range (B) and the red LED lights up outside of the measuring range (A)/(C) in normal operation.

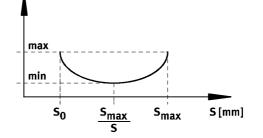


Repetition accuracy

The repetition accuracy is ±0.025 mm on grippers and ±0.1 mm on standard drives.

With standard drives, the repetition accuracy in the centre of the measuring range is lower than at the edge. It is ±0.06 mm at a distance of ±5 mm from the centre, for example. For critical applications, it is recommended that the SMAT-8M be mounted so as to have the relevant measuring points close to 5.5 V.

Repetition accuracy as a function of position measuring range S



Position transmitters SMAT-8M, for T-slot Selection aid

Drive/gripper	Usability on drive	Position me range appro	-	Drive/gripper	Usability on drive	Position me range appro	-
		With ini- tialisation [mm]	Without initialisa- tion ²⁾ [mm]			With ini- tialisation [mm]	Without initialisa- tion ²⁾ [mm]
Standards-based cylinders				Standards-based cylinders		<u> </u>	
Standard cylinder DSBC-32	+	26	26	Compact cylinder AND/AEN-12	+	22	22
Standard cylinder DSBC-40	+	26	26	Compact cylinder ADN/AEN-16	+	26	26
Standard cylinder DSBC-50	+	30	27	Compact cylinder ADN/AEN-20	+	30	28
Standard cylinder DSBC-63	+	33	33	Compact cylinder ADN/AEN-25	+	27	24
Standard cylinder DSBC-80	+	37	37	Compact cylinder ADN/AEN-32	+	31	31
Standard cylinder DSBC-100	+	33	31	Compact cylinder ADN/AEN-40	+	28	20
Standard cylinder DSBC-125	+	35	34	Compact cylinder ADN/AEN-50	+	25	21
Standard cylinder DSBG-32	+	19	17	Compact cylinder ADN/AEN-63	+	31	29
Standard cylinder DSBG-40	+	24	23	Compact cylinder ADN/AEN-80	0 ¹⁾	-	-
Standard cylinder DSBG-50	+	27	26	Compact cylinder ADN/AEN-100	+	28	24
Standard cylinder DSBG-63	+	27	27	Compact cylinder ADN/AEN-125	+	37	33
Standard cylinder DSBG-80	+	30	33				
Standard cylinder DSBG-100	+	29	27	Cylinders with piston rod			
Standard cylinder DSBG-125	+	27	24	Short-stroke cylinder ADVC/AEVC-32	+	Stroke	Stroke
Standard cylinder DSNU/ESNU-8	+	19	17			< position	< position
Standard cylinder DSNU/ESNU-10	+	22	19			measuring	measuring
Standard cylinder DSNU/ESNU-12	+	21	19			range	range
Standard cylinder DSNU/ESNU-16	+	21	19			SMAT-8M	SMAT-8M
Standard cylinder DSNU/ESNU-20	+	20	18	Short-stroke cylinder ADVC/AEVC-40	+	-	24
Standard cylinder DSNU/ESNU-25	+	28	22	Short-stroke cylinder ADVC/AEVC-50	+	_	Stroke
Round cylinder DSNU/ESNU-32	+	25	23				< position
Round cylinder DSNU/ESNU-40	+	29	30	Short-stroke cylinder ADVC/AEVC-63	+		measuring
Round cylinder DSNU/ESNU-50	+	31	29		-		range
Round cylinder DSNU/ESNU-63	+	36	33	Short-stroke cylinder ADVC/AEVC-80	+		SMAT-8M
Standard cylinder DNCB-32	+	25	23	Short-stroke cylinder ADVC/AEVC-100	+	_	24
Standard cylinder DNCB-40	+	28	19	Compact cylinder ADVU/AEVU-12	+	23	20
Standard cylinder DNCB-50	+	30	26	Compact cylinder ADVU/AEVU-16	+	20	17
Standard cylinder DNCB-63	+	32	27	Compact cylinder ADVU/AEVU-20	+	29	28
Standard cylinder DNCB-80	+	35	32	Compact cylinder ADVU/AEVU-25	+	25	20
Standard cylinder DNCB-100	+	29	26	Compact cylinder ADVU/AEVU-32	+	27	23
Standard cylinder DNC-32	+	29	32	Compact cylinder ADVU/AEVU-40	+	24	21
Standard cylinder DNC-40	0 ¹⁾	-	-	Compact cylinder ADVU/AEVU-50	+	22	18
Standard cylinder DNC-50	0 ¹⁾	-	-	Compact cylinder ADVU/AEVU-63	+	32	27
Standard cylinder DNC-63	+	34	28	Compact cylinder ADVU/AEVU-80	+	35	28
Standard cylinder DNC-80	+	35	29	Compact cylinder ADVU/AEVU-100	+	33	26
Standard cylinder DNC-100	+	37	33	Compact cylinder ADVU/AEVU-125	+	35	31
Standard cylinder DNC-125	+	38	32	Flat cylinder DZF-12	+	29	26
Standard cylinder DNG-32	+	28	19	Flat cylinder DZF-18	+	26	24
Standard cylinder DNG-40	+	34	30	Flat cylinder DZF-25	+	28	23
Standard cylinder DNG-50	0 ¹⁾	-	-	Flat cylinder DZF-32	+	26	17
Standard cylinder DNG-63	+	32	25	Flat cylinder DZF-40	0 ¹⁾	-	-
Standard cylinder DNG-80	+	32	25	Flat cylinder DZF-50	0 ¹⁾	-	-
Standard cylinder DNG-100	+	32	27	Flat cylinder DZF-63	0 ¹⁾	-	-

- On request
 Different from technical data. Usability on request.
 Position measuring range without initialisation (as supplied from the factory)

Position transmitters SMAT-8M, for T-slot Selection aid

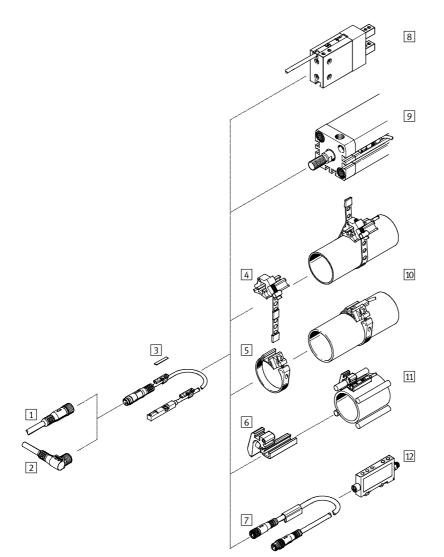
Drive/gripper	Usability	Position me	asuring			
	on drive	range approx.				
	on unive	With ini-	Without			
		tialisation	initialisa-			
		intisution	tion ²⁾			
		[mm]	[mm]			
Dedlage adiadere		[]	[mm]			
Rodless cylinders Linear drive DGC-18	+	30	26			
Linear drive DGC-25	• •	-	-			
Linear drive DGC-32	0 ⁻ , 0 ¹⁾	-	-			
Linear drive DGC-32	0 ^{-,} 0 ¹⁾	-	-			
	0-7	-	-			
Function-oriented drives						
Linear/swivel clamp CLR-12	+	22	22			
Linear/swivel clamp CLR-16	+	26	26			
Linear/swivel clamp CLR-20	+	30	28			
Linear/swivel clamp CLR-25	+	27	20			
Linear/swivel clamp CLR-32	+	31	31			
Linear/swivel clamp CLR-40	+	28	20			
Linear/swivel clamp CLR-50	+	25	20			
Linear/swivel clamp CLR-63	+	31	29			
		51	27			
Drives with linear guides						
Guided drive DFM-12	+	21	22			
Guided drive DFM-16	+	15	16			
Guided drive DFM-20	+	24	22			
Guided drive DFM-25	+	26	25			
Guided drive DFM-32	+	25	22			
Guided drive DFM-40	0 ¹⁾	-	-			
Guided drive DFM-50	+	21	18			
Guided drive DFM-63	+	31	27			
Guided drive DFM-80	+	30	30			
Guided drive DFM-100	+	25	24			
Guided drive DFM-12-B	+	16	22			
Guided drive DFM-16-B	+	20	21			
Guided drive DFM-20-B	+	26	27			
Guided drive DFM-25-B	+	24	22			
Guided drive DFM-32-B	+	29	28			
Guided drive DFM-40-B	+	30	29			
Guided drive DFM-50-B	+	31	31			
Guided drive DFM-63-B	+	33	32			
Linear unit SLE-10	+	22	22			
Linear unit SLE-16	+	21	21			
Linear unit SLE-20	+	20	20			
Linear unit SLE-25	+	28	28			
Linear unit SLE-32	+	25	25			
Linear unit SLE-40	+	29	29			
Linear unit SLE-50	+	31	31			

Drive/gripper	Usability on drive	Position measuring range approx.			
		With ini- tialisation	Without initialisa- tion ²⁾		
		[mm]	[mm]		
Handling units					
Three-point gripper DHDS-32	+	Stroke < pos	ition		
Three-point gripper DHDS-50	+	measuring ra	ange		
Parallel gripper DHPS-10	+	SMAT-8M			
Parallel gripper DHPS-16	+				
Parallel gripper DHPS-20	+				
Parallel gripper DHPS-25	+				
Parallel gripper DHPS-35	+				
Parallel gripper HGPL-63	0 ¹⁾				
Parallel gripper HGPT-40-B	+				
Parallel gripper HGPT-50-B	+				
Parallel gripper HGPT-63-B	+	16	15		
Parallel gripper HGPT-80-B	+	16	12		
Angle gripper DHWS-16	+	Stroke < pos	ition		
Angle gripper DHWS-25	+	measuring ra	ange		
Angle gripper DHWS-32	+	SMAT-8M			
Angle gripper DHWS-40	+				
Radial gripper DHRS-16	+]			
Radial gripper DHRS-25	+]			
Radial gripper DHRS-32	+]			
Radial gripper DHRS-40	+	1			
Radial gripper HGRT-40-A-G2	+]			
Radial gripper HGRT-50-A-G2	0 ¹⁾]			

+ Unrestricted use

- On request
 Different from technical data. Usability on request.
 Position measuring range without initialisation (as supplied from the factory)

Position transmitters SMAT-8M, for T-slot Peripherals overview



Acce	ssories	→ Page/Internet				
1	Connecting cable NEBU-M8G4	10				
2	Connecting cable NEBU-M8W4	10				
3	Inscription label ASLR	10				
4	Mounting kit SMBR-8-8/100-S6, heat-resistant	10				
5	Mounting kit SMBR	10				
6	Mounting SMBZ-8	10				
7	Connecting cable NEBU-M8G4	10				
8	Three-point gripper DHDS	dhds				
	Three-point gripper HGDD	hgdd				
	Parallel gripper DHPS	dhps				
	Parallel gripper HGPD	hgpd				
	Parallel gripper HGPT hgpt					
	Angle gripper DHWS dhws					
	Radial gripper DHRS dhrs					
	Radial gripper HGRT	hgrt				

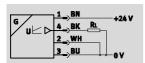
Acce	ssories	→ Page/Internet
9	Standard cylinder DNCB	dncb
	Standard cylinder DNC	dnc
	Compact cylinder ADN	adn
	Short-stroke cylinder ADVC/AEVC	advc
	Compact cylinder ADVU/AEVU	advu
	Flat cylinder DZF	dzf
	Linear drive DGC	dgc
	Linear/swivel clamp CLR	clr
	Guided drive DFM	dfm
10	Standard cylinder/round cylinder DSNU	dsnu
	Linear unit SLE	sle
11	Standard cylinder DSBG	dsbg
12	Signal converter SVE4	sve4

Position transmitters SMAT-8M, for T-slot Type codes

		SMAT	[8	М]-[U	-	E]-	0,3	- [M8D
Туре													
SMAT	Position transmitter, magnetic												
Design													
8	For T-slot												
Sensor	design												
М	Insertable in slot, centre clamping					1							
Switchi	ng input/output												
U 010V								1					
Cable c	naracteristics												
E	Suitable for energy chains/robot applications									1			
Cable le	ngth												
0,3	0.3 m											1	
Electric	al connection												
M8D	M8 plug, 4-pin, rotatable thread												

Technical data

Function Normal operation





General technical data

General technical uata	
Design	For T-slot
Certification	c UL us - Listed (OL)
	C-tick
CE marking (see declaration of conformity)	To EU EMC Directive ¹⁾
Special features	Oil resistant
Note on materials	RoHS-compliant
	Halogen-free

For information about the applicability of the component see the manufacturer's EC declaration of conformity at: www.festo.com → Support → User documentation. If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary.

Input signal/measuring element

···· p ==						
Measuring principle		Magnetic				
Position measuring range	[mm]	$\leq 40^{2}$				

2) Depending on drive/gripper used.

Signal processing		
Max. speed of travel	[m/s]	3
Output, general		

Output, general		
Displacement resolution	[mm]	≤ 0.05 ²⁾
Repetition accuracy	[mm]	±0.1 on cylinders ³⁾
		±0.025 on grippers ³⁾

2) Depending on drive/gripper used.

Use of a non-rotating piston rod or a mechanical structure to protect against rotation is recommended.

Analogue output		
Typical linearity error	[mm]	±1 on cylinders ²⁾
		±0.2 on grippers ²⁾

2) Depending on drive/gripper used.

Electrical outputs			
Analogue output	[V]	0 10	
Protection against short circuit		Yes	
Protection against overloading		Yes	
Output signal		Analogue	

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Technical data

Electronics				
Operating voltage range	[V DC]	15 30		
Typical scanning interval [ms]		2.8		
Protection against polarity reversal		For all electrical connections		

Electromechanics		
Electrical connection		Cable with plug, M8x1, knurled ring, 4-pin
Ambient temperature with flexible	[°C]	-5 +70
cable installation		
Cable length	[m]	0.3
Cable characteristics		Energy chain + robots
Cable test conditions		Energy chain: 50,000 cycles, bending radius 30 mm
		Torsional strength: >300,000 cycles, ±270°/0.1 m
		Resistance to bending: to Festo standard; test conditions on request
Information on materials for cable sheath		TPE-U(PUR)

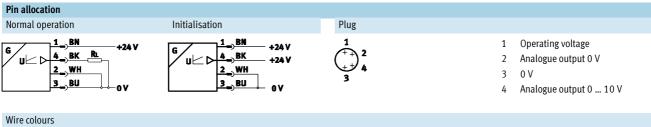
Mechanical components				
Type of mounting		Secured with screw, insertable in the slot from above		
Product weight	[g]	10		
Information on housing materials		Reinforced PA6		

Display/operation			
Status display	LED red, green		

Immissions/emissions				
Ambient temperature	[°C]	-25 +75		
Protection class		IP65, IP68		
Corrosion resistance class	CRC ⁴⁾	2		

4) Corrosion resistance class 2 as per Festo standard 940 070

Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

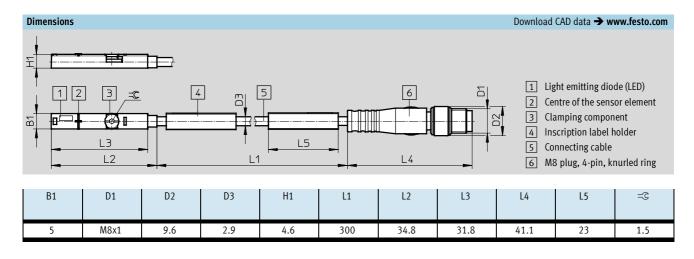


BN = brown BK = black

BU = blue WH = white

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Technical data



Ordering data					
Size	Analogue output [V]	Electrical connection	Cable length [m]	Part No.	Туре
STREET, STREET,	0 10	M8 plug, 4-pin, rotatable thread	0.3	553744	SMAT-8M-U-E-0,3-M8D

Ordering da	ta – Mounting attachments		
	For piston diameter	Part No.	Туре
Mounting ki	it SMBR-8-8/100-S6, heat-resistant		
	8 100	538937	SMBR-8-8/100-S6
Mounting ki	it SMBR		
	8	175091	SMBR-8-8
	10	175092	SMBR-8-10
\bigcirc	12	175093	SMBR-8-12
	16	175094	SMBR-8-16
	20	175095	SMBR-8-20
	25	175096	SMBR-8-25
	32	175097	SMBR-8-32
	40	175098	SMBR-8-40
	50	175099	SMBR-8-50
	63	175100	SMBR-8-63
Mounting SM	MBZ		
BOM	32 100	537806	SMBZ-8-32/100
	125 320	537808	SMBZ-8-125/320

Ordering data	– Connecting cable NEBU-M8				Technical data 🗲 Internet: nebu
	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Туре
and a	Straight socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541342	NEBU-M8G4-K-2.5-LE4
• • • • •			5	541343	NEBU-M8G4-K-5-LE4
5.55 P	Straight socket, M8x1, 4-pin	Straight socket, M8x1, 4-pin	2.5	554035	NEBU-M8G4-K-2.5-M8G4
	Angled socket, M8x1, 4-pin	Cable, open end, 4-wire	2.5	541344	NEBU-M8W4-K-2.5-LE4
STE OU			5	541345	NEBU-M8W4-K-5-LE4

Ordering data – Inscription label ASLR						
	Size	Part No.	Туре	PU ¹⁾		
	23x4 mm	541598	ASLR-L-423	34		

1) Packaging unit in quantity per frame